Flight Demonstration of Novel Atmospheric Satellite Concept



Completed Technology Project (2016 - 2018)

Project Introduction

The Dual-Aircraft Platform (DAP) is a novel concept for achieving a low-cost atmospheric satellite in the lower stratosphere which utilizes a combination of wind and solar energy capture. DAP consists of two glider-like unmanned aircraft connected via a thin, ultra-strong cable. Long duration flight simulations have shown the platform could literally sail without propulsion, using levels of wind shear persistently found near 60,000-ft, and substantially increase the energy available for useful payload operations. #The central objective of the proposed Phase II effort is to perform autonomous proof-ofconcept flight demonstrations of the DAP concept using a small-scale prototype at low altitude. Related objectives are develop specific flight maneuvers and mechanisms required for station keeping, and validate the autonomous guidance and control software. #Flight demonstrations of the sailing mode of operation, as well as all other required maneuvers for stratospheric station keeping, will be conducted using the atmospheric onshore wind shear produced at low altitudes (< 500 feet) at Kennedy Space Center's (KSC) Shuttle Landing Facility. Optimal dates/times for flight testing will be selected based on an historical weather assessment. Off-the shelf aircraft will be modified for DAP operation. The aircraft will be remotely controlled by KSC pilots during the first year, and will gradually shift towards complete autonomous flight control in the second year. Flight software will be developed and validated within the hardware-in-the-loop DAP flight simulator at Embry-Riddle Aeronautical University. #Atmospheric satellites represent a long-standing, grand challenge to the aeronautics community, and have enormous potential societal and economic impact. Such airborne platforms are expected to diversify and expand surveillance capabilities (e.g., NASA's earth science missions) and communications bandwidth and availability (e.g., for underserved remote areas of the US, emergency communications), at a fraction of the cost of orbital satellite networks. Successful proof-of-concept DAP flight demonstrations are expected to lead to commercial investment to build a large scale prototype.



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Prototype aircraft with pitot probe and 7-hole air data probe on opposite wings

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Primary U.S. Work Locations and Key Partners



Organizations Performing Work	Role	Туре	Location
Embry-Riddle Aeronautical University-Daytona Beach	Lead Organization	Academia	Daytona Beach, Florida
Kennedy SpaceCenter(KSC)	Supporting Organization	NASA Center	Kennedy Space Center, Florida
Marshall Space Flight Center(MSFC)	Supporting Organization	NASA Center	Huntsville, Alabama

Primary U.S. Work Locations

Florida

Project Transitions



Organizational Responsibility

Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

Lead Organization:

Embry-Riddle Aeronautical University-Daytona Beach

Responsible Program:

NASA Innovative Advanced Concepts

Project Management

Program Director:

Jason E Derleth

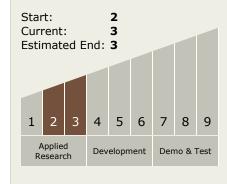
Program Manager:

Eric A Eberly

Principal Investigator:

William Engblom

Technology Maturity (TRL)





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June 2018: Closed out

Closeout Summary: The major focus of the Phase II effort described herein wa s to develop and demonstrate an aircraft capable of autonomously sailing (i.e., t o cruise without propulsion or external assistance), and thereby prove that the d ual-aircraft platform (DAP) atmospheric satellite concept is potentially viable. Th is sailing mode of flight was identified as the #1 enabling technology required fo r the DAP concept in the Phase I effort. No scientific demonstration of this techn ology has ever been done to our knowledge. Great strides were made towards d evelopment of the enabling technology. A specialized prototype aircraft was dev eloped including a novel cable release mechanism, novel lateron control surface s, and a highly-accurate onboard wind measurement system. All of these device s were developed in house and validated in flight testing. A specialized flight sim ulator was constructed and utilized to develop the autonomous flight controller r equired onboard the aircraft, as support training of pilots for flying aircraft while tethered to a ground vehicle. Software has been developed to provide look-up ta bles that give the flight condition targets (i.e., 3-D position relative to ground ve hicle), speed, orientation, and cable length, based on current wind speed and dir ection. These tables have been successfully validated in flight simulation and us ed onboard the aircraft. The aerodynamics of this aircraft were characterized wit h high fidelity analysis, as needed to produce accurate target sailing flight condit ions. The aerodynamics of the cable was also accurately characterized using a n ovel wind tunnel measurement technique. Finally, novel auto-tuning software ha s been developed to refine the sailing flight condition targets based on an optimi zation technique involving doublet maneuvers. Although a real-world demonstra tion of the sailing mode of flight was not achieved during the Phase II effort, the concept has been further validated using detailed flight simulations and in precu rsor real-world flight tests. Virtual flights using the auto-tuning software indicate that the prototype aircraft should be able to reach and hold sailing conditions de spite moderate levels of turbulence provided there is sufficient mean wind availa ble. Hundreds of flight tests using primarily a dead runway at Deland Municipal Airport, and the long runway at Space Florida's Shuttle Landing Facility, resulted in successful demonstration of the closed-loop autonomous formation flight capa bility. Future work should include flight testing (and refinement) of the auto-tun e software to refine the aircraft orientation targets and achieve and hold the saili ng mode of flight. It is also suggested that higher fidelity onboard avionics may be necessary to facilitate sailing by reducing sensor errors. Although the DAP fli ght simulator, developed within the Matlab-Simulink framework, includes detaile d treatment of aircraft/cable aerodynamics, cable dynamics, experimentally-deri ved propeller-motor thrust curves, and realistic air turbulence, realistic emulatio n of various sensor errors, more realistic actuator responsiveness, and hardware -in-the-loop testing is highly desirable to improve the fidelity of flight simulation evaluations of the onboard flight software.

Closeout Link: https://www.nasa.gov/feature/flight-demonstration-of-novel-at mospheric-satellite-concept

Technology Areas

Primary:

- TX15 Flight Vehicle Systems
 TX15.1 Aerosciences
 - ☐ TX15.1.6 Advanced Atmospheric Flight Vehicles

Target Destination Earth



NASA Innovative Advanced Concepts

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Images



Project ImagePrototype aircraft with pitot probe and 7-hole air data probe on opposite wings
(https://techport.nasa.gov/imag e/102126)

Links

NASA.gov Feature Article (https://www.nasa.gov/feature/flight-demonstration-of-novel-atmospheric-satellite-concept)

